

AVEC LE SOUTIEN DU FONDS EUROPÉEN DE DÉVELOPPEMENT RÉGIONAL MET STEUN VAN HET EUROPEES FONDS VOOR REGIONALE ONTWIKKELING

Projet N° 4.7.360 - Project N° 4.7.360

## N(E)MADe

6 MÉDECINE PHYSIQUE

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### Machine Learning Can be Used to Predict and Identify Acute Neck Pain Patients Assessed with the DidRen laser test

Renaud Hage, Frédéric Dierick, Fabien Buisseret, Lecointre Julien, Martin Houry.

16/10/21





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Neck Pain

## Definition

Unpleasant sensory and emotional experience associated with real or potential tissue damage in the neck region.





**Neck Pain** 





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## Prevalence

## « Top Ten » Causes of Years Lived with Disability in Belgique/France.

Vos et al. in The Lancet, 2015







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## Prevalence



Neck pain has a high prevalence in developed countries

(Fejer et al. 2006; Blanpied 2017)





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## **Important Considerations**

### Neck Pain

Improving **Understanding** of the pathophysiological mechanisms **AND Management** of neck pain

Conducting observational **Sensorimotor Assessment** studies **using large databases** holds great promise (Tack, 2019; Sjolander 2008; de Zoete 2016; Treleaven 2017).

**Machine learning** is a field of artificial intelligence that can be used to **predict** status of Acute Non-Specific Neck Pain Patients and **identify** discriminative data (Tack, 2019).



**Neck Pain** 



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## The Objective of this Study

 Evaluate the potential usefulness of Artificial Intelligence methods in the assessment of Sensorimotor Performance of the neck with the DidRen laser test of Acute Neck Pain Patients compared to healthy control.

- Thanks to dataset obtained during Sensorimotor Performance (DidRen laser test):
  - N=80 (38 Neck Pain Patients/42 Healthy Controls)



Peer

#### Age-related kinematic performance should

be considered during fast head-neck rotation target task in individuals aged from 8 to 85 years old

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Renaud Hage<sup>1\*</sup>, Fabien Buisseret<sup>2</sup>, Laurent Pitance<sup>1,3</sup>, Jean-Michel I Christine Detrembleur<sup>1</sup>, Frédéric Dierick<sup>2</sup>



EUROPERIOR DE DÉVELOPREMENT RÉGIONAL

Enregistrement de l'écran 🔅 DATA 📈 GRAPH 😭 VIEW 🧃 ABOUT O AngCX Sensor N°0 64 18 -16 -48 -64 -80 0.0 Time [s] (1 mark = 1 [s]) 20.0 Max : [deg] Sensor : Data : Min: [deg]

Development of a <u>valid</u> and <u>reliable</u> test to assess the sensorimotor function during Cervical Rotation: « DidRen Laser Test » (Hage et al. 2009; 2019).

	Measured with a <u>Validated Inertial Sensor</u> : DYSKIMOT	
5015	(Hage et al. 2019).	
3073		

**Gyroscope=Angular displacement** (Deg/s) and **Acceleromter=Acceleration** (g)

sensors

DYSKIMOT: An ultra-low-cost inertial sensor to assess head's rotational kinematics in adults during the Didren-Laser Test

2	RECORD:	Start date :	21/02/19 19:19	End date :	21/02/19 19:20	Time [hh:mm:ss]:	00:00:52	Frequency [Hz
3								
4	Time [s]	AccX [g]	AccY [g]	AccZ [g]	GyrX [deg/s]	GyrY [deg/s]	GyrZ [deg/s]	
5	0	0	0	0	0	0	0	
6	0.01	0.98	0.01	0.07	0.28	3.43	1.75	
7	0.02	0.99	0.01	0.07	0.07	3.22	1.54	
8	0.03	0.98	0.02	0.07	0.7	3.15	1.4	
9	0.04	0.98	0.02	0.07	0.98	2.87	1.19	
10	0.05	0.98	0.03	0.06	1.89	2.59	0.84	
1	0.06	0.98	0.03	0.06	2.59	2.8	0.49	
12	0.07	0.98	0.03	0.07	3.01	2.66	0.07	
13	0.08	0.98	0.02	0.07	4.06	2.31	-0.07	
14	0.09	0.98	0.02	0.07	4.13	2.73	0.07	
15	0.1	0.98	0.02	0.06	4.9	2.73	-0.28	
16	0.11	0.98	0.01	0.07	5.18	2.8	-0.49	
17	0.12	0.98	0.01	0.06	5.18	2.87	-0.14	
18	0.13	0.98	0.01	0.07	5.25	3.01	-0.7	
19	0.14	0.98	0	0.07	5.04	2.73	-0.77	
20	0.15	0.98	0	0.07	4.9	2.59	-1.19	
21	0.16	0.98	0	0.07	4.9	2.59	-1.12	
22	0.17	0.99	0	0.07	4.62	2.87	-0.7	
23	0.18	0.99	0	0.07	4.27	2.52	-0.77	
24	0.19	0.99	0	0.07	3.99	2.52	-0.63	
25	0.2	0.98	0	0.07	3.36	2.45	-0.28	
26	0.21	0.98	0	0.06	3.5	2.38	0.07	
27	0.22	0.98	0.01	0.07	3.64	1.89	-0.07	
28	0.23	0.98	0.01	0.07	3.78	1.68	-0.21	
29	0.24	0.98	0.02	0.07	3.99	1.4	-0.42	
30	0.25	0.98	0.01	0.08	3.85	1.68	-0.28	
31	0.26	0.98	0.01	0.08	4.06	1.26	-0.56	
32	0.27	0.98	0.01	0.08	3.85	1.61	-0.49	
33	0.28	0.97	0.01	0.08	4.27	1.82	-0.14	
34	0.29	0.98	0.01	0.08	3.85	2.24	0.07	
35	0.3	0.97	0.01	0.08	4.27	2.24	-0.35	
36	0.31	0.98	0.01	0.07	4.2	2.38	-0.49	
37	0.32	0.97	0.01	0.08	4.55	2.17	-0.84	
38	0.33	0.97	0.01	0.08	3.99	2.8	-0.7	
20	0.24	0.00	0.01	0.00	4.24	2.01	0.77	

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2	RECORD:	Start date :	21/02/19 19:19	End date :	21/02/19 19:20	Time [hh:mm:ss]:	00:00:52	Frequency [Hz
3	<b>T</b> ( )	A	A		0. 11. (1)	C . V(1 - / 1	0.7(1.7)	
4	Time [s]	AccX [g]	Accy [g]	AccZ [g]	GyrX [deg/s]	Gyry [deg/s]	GyrZ [deg/s]	
5	0	0	0	0	0	0	0	
6	0.01	0.98	0.01	0.07	0.28	3.43	1.75	
1	0.02	0.99	0.01	0.07	0.07	3.22	1.54	
8	0.03	0.98	0.02	0.07	0.7	3.15	1.4	
9	0.04	0.98	0.02	0.07	0.98	2.87	1.19	
10	0.05	0.98	0.03	0.06	1.89	2.59	0.84	
11	0.06	0.98	0.03	0.06	2.59	2.8	0.49	
12	0.07	0.98	0.03	0.07	3.01	2.66	0.07	
13	0.08	0.98	0.02	0.07	4.06	2.31	-0.07	
14	0.09	0.98	0.02	0.07	4.13	2.73	0.07	
15	0.1	0.98	0.02	0.06	4.9	2.73	-0.28	
16	0.11	0.98	0.01	0.07	5.18	2.8	-0.49	
17	0.12	0.98	0.01	0.06	5.18	2.87	-0.14	
18	0.13	0.98	0.01	0.07	5.25	3.01	-0.7	
19	0.14	0.98	0	0.07	5.04	2.73	-0.77	
20	0.15	0.98	0	0.07	4.9	2.59	-1.19	
21	0.16	0.98	0	0.07	4.9	2.59	-1.12	
22	0.17	0.99	0	0.07	4.62	2.87	-0.7	
23	0.18	0.99	0	0.07	4.27	2.52	-0.77	
24	0.19	0.99	0	0.07	3.99	2.52	-0.63	
25	0.2	0.98	0	0.07	3.36	2.45	-0.28	
26	0.21	0.98	0	0.06	3.5	2.38	0.07	
27	0.22	0.98	0.01	0.07	3.64	1.89	-0.07	
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29	0.24	0.98	0.02	0.07	3.99	1.4	-0.42	
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35	0.3	0.97	0.01	0.08	4.27	2.24	-0.35	
36	0.31	0.98	0.01	0.07	4.2	2.38	-0.49	
37	0.32	0.97	0.01	0.08	4.55	2.17	-0.84	
38	0.33	0.97	0.01	0.08	3.99	2.8	-0.7	
20	0.24	0.00	0.01	0.00	1 2 4	2.01	77 0	





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2	RECORD:	Start date :	21/02/19 19:19	End date :	21/02/19 19:20	Time [hh:mm:ss]:	00:00:52	Frequency [Hz
3						a	0.7/1./1	
4	Time [s]	AccX [g]	AccY [g]	AccZ [g]	GyrX [deg/s]	GyrY [deg/s]	GyrZ [deg/s]	
5	0	0	0	0	0		0 0	
6	0.01	0.98	0.01	0.07	0.28	3.4	3 1.75	
7	0.02	0.99	0.01	0.07	0.07	3.2	2 1.54	
8	0.03	0.98	0.02	0.07	0.7	3.1	5 1.4	
9	0.04	0.98	0.02	0.07	0.98	2.8	7 1.19	
10	0.05	0.98	0.03	0.06	1.89	2.5	9 0.84	
11	0.06	0.98	0.03	0.06	2.59	2.	8 0.49	
12	0.07	0.98	0.03	0.07	3.01	2.6	6 0.07	
13	0.08	0.98	0.02	0.07	4.06	2.3	1 -0.07	
14	0.09	0.98	0.02	0.07	4.13	2.7	3 0.07	
15	0.1	0.98	0.02	0.06	4.9	2.7	3 -0.28	
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17	0.12	0.98	0.01	0.06	5.18	2.8	7 -0.14	
18	0.13	0.98	0.01	0.07	5.25	3.0	1 -0.7	
19	0.14	0.98	0	0.07	5.04	2.7	3 -0.77	
20	0.15	0.98	0	0.07	4.9	2.5	9 -1.19	
21	0.16	0.98	0	0.07	4.9	2.5	9 -1.12	
22	0.17	0.99	0	0.07	4.62	2.8	7 -0.7	
23	0.18	0.99	0	0.07	4.27	2.5	2 -0.77	
24	0.19	0.99	0	0.07	3.99	2.5	2 -0.63	
25	0.2	0.98	0	0.07	3.36	2.4	5 -0.28	
26	0.21	0.98	0	0.06	3.5	2.3	8 0.07	
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30	0.25	0.98	0.01	0.08	3.85	1.6	8 -0.28	
31	0.26	0.98	0.01	0.08	4.06	1.2	6 -0.56	
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37	0.32	0.97	0.01	0.08	4.55	2.1	7 -0.84	
38	0.33	0.97	0.01	0.08	3.99	2.	8 -0.7	
20	0.24	0.00	0.01	0.00	1 24	2.0	1 0.77	



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6	0.01	0.98	0.01	0.0	0.28	3.43	1.75	
7	0.02	0.99	0.01	0.0	0.07	3.22	1.54	
8	0.03	0.98	0.02	0.0	0.7	3.15	1.4	
9	0.04	0.98	0.02	0.0	0.98	2.87	1.19	
10	0.05	0.98	0.03	0.0	5 1.89	2.59	0.84	
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28	0.23	0.98	0.01	0.0	3.78	1.68	-0.21	
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38	0.33	0.97	0.01	0.0	3.99	2.8	-0.7	
20	0.34	0.00	0.01	0.01	1 1 1	2 01	0.77	



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# 3 stageschine Learning – How does it work?

- Machine Learning algorithms <u>learns</u> and <u>acquire experience</u> based on datasets...<u>to predict</u>....
- Learn ..... main differences between the populations.
- <u>Acquire Experience</u> ...... <u>to predict</u> their appartenance of Healthy Control Participants or Acute Neck Pain Patients.





## Stage chine Learning - How does it work?

 The <u>training</u> help the Machine Learning algorithms to <u>identify</u> the usual main differences between Patients datasets and Control Subject datasets.





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## Machine Learning – How does it work?

Main differences

Gyroscope Y values are higher in Control Subject datasets

Acceleromer Z values are higher in Patient datasets







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WET STEEN VAN HET ELIKOPEEN (CNOS VOOR RESIONALE ONTWIKE)

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• New datasets are evaluated by the trained machine leanrning algorithm.





## stage<sup>3</sup> chine Learning – How does it work?

- Datasets are evaluated by the trained machine learning algorithm.
- Then the predictions are compared to reality (Human controled dataset)





## **Machine Learning – Results**

• After feature selection, model selection and hyper-parameters optimizations :

82,4% Accuracy

**79,6%** AUC





## **Machine Learning – Results**

• The best peforming sensor axe for predictions has been computed with Sequential Feature Selection methods (SFS backward/forward).

## Gyroscope Y

Most useful sensor axe for accurate predictions





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## **Machine Learning – Results**

- Clinical Implications:
  - During Rotation (primary movement), it is the Flexion/Extension (secondary movement) that seems to discriminate patients from healthy subjects.

 Clinical observation of movement focuses on the evaluation of speed, saccades and especially changes in the axis of movement



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# N(E)MADe

ECOSYSTÈME D'APPRENTISSAGE, R&D ET EXPERTISE TRANSFRONTALIER DÉDIÉ AUX TROUBLES NEURO-MUSCULO-SQUELETTIQUES LEERECOSYSTEEM, O&O EN GRENSOVERSCHRIJDENDE EXPERTISE GEWIJD AAN NEURO-MUSCULOSKELETALE AANDOENINGEN

